

## Mathematical Equations

## Equations in Unit 1, Kinematics

Equation	Variables	Name, if any
$\Delta \vec{d} = \vec{d}_2 - \vec{d}_1$	$\Delta \vec{d}$ = displacement $\vec{d}_1$ = initial position $\vec{d}_2$ = final position	displacement
$\vec{v}_{\text{ave}} = \frac{\Delta \vec{d}}{\Delta t}$ $\vec{v}_{\text{ave}} = \frac{\vec{d}_2 - \vec{d}_1}{t_2 - t_1}$	$\vec{v}_{\text{ave}}$ = average velocity $\Delta \vec{d}$ = displacement $\Delta t$ = time interval	average velocity
$\vec{a} = \frac{\Delta \vec{v}}{\Delta t}$	$\vec{a}$ = acceleration $\Delta \vec{v}$ = change in velocity $\Delta t$ = time interval	acceleration
$a = \frac{v_f - v_i}{\Delta t}$ $v_f = v_i + a\Delta t$ $\Delta d = \left(\frac{v_i + v_f}{2}\right) \Delta t$ $\Delta d = v_i \Delta t + \frac{1}{2} a \Delta t^2$	$a$ = acceleration $v_i$ = initial velocity $v_f$ = final velocity $\Delta t$ = time interval $\Delta d$ = displacement	motion under uniform acceleration

## Equations in Unit 2, Dynamics

Equation	Variables	Name, if any
$\vec{F}_g = m\vec{g}$	$\vec{F}_g$ = force of gravity (weight) $m$ = mass $\vec{g}$ = acceleration due to gravity (on Earth)	weight
$F_f = \mu F_N$	$F_f$ = force of friction $\mu$ = coefficient of friction $F_N$ = normal force	friction
$\vec{F} = m\vec{a}$ $\vec{a} = \frac{\vec{F}}{m}$	$\vec{F}$ = force $m$ = mass $\vec{a}$ = acceleration	Newton's second law
$\vec{F}_{A \text{ on } B} = -\vec{F}_{B \text{ on } A}$	$\vec{F}_{A \text{ on } B}$ = force of object A acting on object B $\vec{F}_{B \text{ on } A}$ = force of object B acting on object A	Newton's third law
$\vec{p} = m\vec{v}$	$\vec{p}$ = momentum $m$ = mass $\vec{v}$ = velocity	momentum
$\vec{J} = \vec{F}\Delta t$	$\vec{J}$ = impulse $\vec{F}$ = force $\Delta t$ = time interval	impulse
$\vec{F}\Delta t = m\vec{v}_2 - m\vec{v}_1$	$\vec{F}$ = force $\Delta t$ = time interval $m$ = mass $\vec{v}_1$ = initial velocity $\vec{v}_2$ = final velocity	impulse-momentum theorem

## Equations in Unit 3, Momentum and Energy

Equation	Variables	Name, if any
$W = F_{\parallel} \Delta d$ $W =  F  \Delta d \cos \theta$	$W$ = work done $F_{\parallel}$ = magnitude of the force (parallel to the displacement) $ F $ = magnitude of the force (not parallel to the displacement) $\Delta d$ = magnitude of the displacement $\theta$ = angle between force and displacement vectors	work done
$E_k = \frac{1}{2}mv^2$	$E_k$ = kinetic energy $m$ = mass $v$ = velocity	kinetic energy
$E_g = mg\Delta h$	$E_g$ = gravitational potential energy $m$ = mass $g$ = acceleration due to gravity (on Earth) $\Delta h$ = change in height (from reference position)	gravitational potential energy
$F = -kx$	$F$ = applied force $k$ = spring constant $x$ = length of extension/compression of spring	Hooke's law
$E_e = \frac{1}{2}kx^2$	$E_e$ = elastic energy $k$ = spring constant $x$ = length of extension/compression	elastic potential energy
$P = \frac{W}{\Delta t}$ $P = \frac{E}{\Delta t}$	$P$ = power $E$ = energy transferred $W$ = work done $\Delta t$ = time interval	power
efficiency = $\frac{E_o}{E_i} \times 100\%$ efficiency = $\frac{W_o}{W_i} \times 100\%$	$E_o$ = useful output energy $E_i$ = input energy $W_o$ = useful output work $W_i$ = input work efficiency	efficiency
$E'_k + E'_g + E'_e = E_k + E_g + E_e$	$E'_k$ = kinetic energy after process $E'_g$ = gravitational potential energy after process $E'_e$ = elastic potential energy after process $E_k$ = kinetic energy before process $E_g$ = gravitational potential energy before process $E_e$ = elastic potential energy before process	law of conservation of mechanical energy
$W_{nc} = E_{\text{final}} - E_{\text{initial}}$	$W_{nc}$ = work done by non-conservative forces $E_{\text{final}}$ = mechanical energy of system after process $E_{\text{initial}}$ = mechanical energy of system before process	work done by non-conservative forces
$m_A \vec{v}_A + m_B \vec{v}_B = m_A \vec{v}'_A + m_B \vec{v}'_B$	$M_A$ = mass of object A $M_B$ = mass of object B $\vec{v}_A$ = velocity of object A before collision $\vec{v}_B$ = velocity of object B before collision $\vec{v}'_A$ = velocity of object A after collision $\vec{v}'_B$ = velocity of object B after collision	law of conservation of momentum

## Equations in Unit 4, Waves

Equation	Variables	Name, if any
$T = \frac{\Delta t}{N}$ $f = \frac{N}{\Delta t}$ $f = \frac{1}{T}$	$T$ = period $f$ = frequency $\Delta t$ = time interval $N$ = number of cycles	period and frequency
$v = f\lambda$	$v$ = speed $f$ = frequency $\lambda$ = wavelength	wave equation
$v = 331 + 0.59T_C$	$v$ = speed of sound $T_C$ = temperature of air	speed of sound in air
$n = \frac{c}{v}$	$n$ = index of refraction $c$ = speed of light in vacuum $v$ = speed of light in a specific medium	index of refraction
$\frac{\sin \theta_i}{\sin \theta_r} = \text{constant}$ $n_i \sin \theta_i = n_r \sin \theta_r$	$n_i$ = index of refraction of the incidence medium $\theta_i$ = angle of incidence $n_r$ = index of refraction of the refracting medium $\theta_r$ = angle of refraction	Snell's law
$L_n = (2n - 1)\frac{\lambda}{4}$	$L_n$ = resonance lengths $n$ = a positive integer $\lambda$ = wavelength	resonance lengths in a closed air column
$L_n = \frac{n\lambda}{4}$	$L_n$ = resonance lengths $n$ = a positive integer $\lambda$ = wavelength	resonance lengths in an open air column
$f_n = nf_1$ $f_1 = \frac{v}{2L}$	$f_n$ = resonance frequencies $n$ = a positive integer $f_1$ = first resonance frequency $v$ = speed of wave $L$ = air column length	resonance frequencies of a fixed-length open air column
$f_n = (2n - 1)f_1$ $f_1 = \frac{v}{4L}$	$f_n$ = resonance frequencies $n$ = a positive integer $f_1$ = first resonance frequency $v$ = speed of wave $L$ = air column length	resonance frequencies of a fixed-length closed air column
$f_{\text{beat}} =  f_2 - f_1 $	$f_{\text{beat}}$ = beat frequency $f_1$ = frequency of one component wave $f_2$ = frequency of other component wave	beat frequency
$n\lambda = d \sin \theta$ where $n = 0, 1, 2, 3, \dots$	$n$ = integer number of full wavelengths $\lambda$ = wavelength of light $d$ = distance between slits $\theta$ = angle between slit separation and line perpendicular to light rays	constructive interference of light waves (bright fringe)

Equation	Variables	Name, if any
$\left(n - \frac{1}{2}\right) \lambda = d \sin \theta$ where $n = 0, 1, 2, 3, \dots$	$n$ = integer number of full wavelengths $\lambda$ = wavelength of light $d$ = distance between slits $\theta$ = angle between slit separation and line perpendicular to light rays	destructive interference of light waves (dark fringe)
$\lambda = \frac{\Delta y d}{x}$	$\lambda$ = wavelength of light $\Delta y$ = distance separating adjacent fringes $d$ = distance between slits $x$ = distance from source to screen	approximate wavelength of light

## Equations in Unit 5, Force, Motion, Work, and Energy

Equation	Variables	Name, if any
$A_x =  \vec{A}  \cos \theta$ $A_y =  \vec{A}  \sin \theta$	$\vec{A}$ = vector making an angle $\theta$ with the $x$ -axis $A_x$ = $x$ -component $A_y$ = $y$ -component $\theta$ = angle between vector and $x$ -axis	vector components
$\tau = r_{\perp} F$	$\tau$ = torque $F$ = magnitude of force $r_{\perp}$ = lever arm	torque
$\sum \vec{F} = 0$ $\sum \tau = 0$	$\sum \vec{F}$ = sum of all forces acting on object $\sum \tau$ = sum of all torques acting on object	condition for static equilibrium
$\vec{p} = m\vec{v}$	$\vec{p}$ = momentum $m$ = mass $\vec{v}$ = velocity	momentum
$m_A \vec{v}_A + m_B \vec{v}_B = m_A \vec{v}'_A + m_B \vec{v}'_B$	$m_A$ = mass of object A $m_B$ = mass of object B $\vec{v}_A$ = velocity of object A before collision $\vec{v}_B$ = velocity of object B before collision $\vec{v}'_A$ = velocity of object A after collision $\vec{v}'_B$ = velocity of object B after collision	law of conservation of momentum
$a_c = \frac{v^2}{r}$	$a_c$ = centripetal acceleration $v$ = velocity (magnitude) $r$ = radius (of circle)	centripetal acceleration
$F_c = \frac{mv^2}{r}$	$F_c$ = centripetal force $m$ = mass $v$ = velocity $r$ = radius of circular path	centripetal force
$\frac{r^3}{T^2} = k$ $\frac{r_A^3}{T_A^2} = \frac{r_B^3}{T_B^2}$ where A and B are two planets	$r$ = distance from the Sun $T$ = period of planet's revolution $k$ = constant	Kepler's laws

Equation	Variables	Name, if any
$F_g = G \frac{m_1 m_2}{r^2}$	$F_g$ = force of gravity $G$ = universal gravitational constant $m_1$ = first mass $m_2$ = second mass $r$ = distance between centres of two masses	Newton's law of universal gravitation
$E_T = \frac{1}{2}mv^2 + \frac{1}{2}kx^2$	$E_T$ = total energy of system $m$ = mass $v$ = speed of the mass at position $x$ $k$ = spring constant $x$ = distance of mass from equilibrium position	total energy of mass and spring system
$T = 2\pi\sqrt{\frac{m}{k}}$	$T$ = period $m$ = mass $k$ = spring constant	period of mass on spring
$T = 2\pi\sqrt{\frac{\ell}{g}}$	$T$ = period of pendulum $\ell$ = length of pendulum $g$ = acceleration due to gravity	period of pendulum

### Equations in Unit 6, Electric, Gravitational, and Magnetic Fields

Equation	Variables	Name, if any
$F_Q = k \frac{q_1 q_2}{r^2}$	$F_Q$ = electrostatic force between charges $k$ = Coulomb's constant $q_1$ = electric charge on object 1 $q_2$ = electric charge on object 2 $r$ = distance between object centres	Coulomb's law
$\vec{E} = \frac{\vec{F}_Q}{q}$	$\vec{E}$ = electric field intensity $\vec{F}_Q$ = electric force $q$ = electric charge	electric field intensity
$\vec{g} = \frac{\vec{F}_g}{m}$	$\vec{g}$ = gravitational field intensity $\vec{F}_g$ = gravitational force $m$ = mass	gravitational field intensity
$ \vec{E}  = k \frac{q}{r^2}$	$ \vec{E} $ = electric field intensity $k$ = Coulomb's constant $q$ = source charge $r$ = distance from centre of source	electric field intensity near a point charge
$ \vec{g}  = G \frac{m_s}{r^2}$	$ \vec{g} $ = gravitational field intensity $G$ = universal gravitational constant $m$ = mass of source of field $r$ = distance from centre of source	gravitational field intensity near a point mass
$E_g = -G \frac{Mm}{r}$	$E_g$ = gravitational potential energy $G$ = universal gravitational constant $M$ = mass of planet or celestial body $m$ = mass of object $r$ = distance from centre of planet or celestial body	gravitational potential energy

Equation	Variables	Name, if any
$V = k \frac{q}{r}$	$V$ = electric potential difference $k$ = Coulomb's constant $q$ = electric charge $r$ = distance from centre of charge to point charge	electric potential difference due to a point charge
$V = \frac{\Delta E_Q}{Q}$	$V$ = electric potential difference $\Delta E_Q$ = change in electrical potential energy $Q$ = quantity of charge	electric potential difference between two points in a circuit
$I = \frac{Q}{\Delta t}$	$I$ = current $Q$ = amount of charge $\Delta t$ = time interval	electric current
$Q = Ne$	$Q$ = amount of charge $N$ = number of elementary charges $e$ = elementary charge	amount of charge
$R = \rho \frac{L}{A}$	$R$ = resistance $\rho$ = resistivity $L$ = length of conductor $A$ = cross-sectional area	resistance
$V = IR$	$V$ = potential difference $I$ = current $R$ = resistance	Ohm's law
$R_{\text{eq}} = R_1 + R_2 + R_3 + \dots + R_N$	$R_{\text{eq}}$ = equivalent resistance $R_1, R_2, R_3, \dots R_N$ = resistance of individual loads	equivalent resistance of loads in series
$\frac{1}{R_{\text{eq}}} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots + \frac{1}{R_N}$	$R_{\text{eq}}$ = equivalent resistance $R_1, R_2, R_3, \dots R_N$ = resistance of individual loads	equivalent resistance of resistors in parallel
$V_S = \xi - V_{\text{int}}$	$V_S$ = terminal voltage $\xi$ = electromotive force $V_{\text{int}}$ = internal potential drop of battery	terminal voltage
$P = IV$ $P = \frac{V^2}{R}$ $P = I^2R$	$P$ = power $I$ = current $V$ = potential difference $R$ = resistance	electric power
$B_{\perp} = \frac{F}{IL}$ $L = n\ell$	$B$ = magnetic field strength $\perp$ = perpendicular to $F$ = motor force $I$ = current $L$ = length of conductor $n$ = number of coil turns $\ell$ = length of each turn	magnetic field strength

## Equations in Unit 7, Waves and Modern Physics

Equation	Variables	Name, if any
$\Delta t = \frac{\Delta t_0}{\sqrt{1 - \frac{v^2}{c^2}}}$	$\Delta t$ = dilated time $\Delta t_0$ = proper time $v$ = velocity of moving reference frame $c$ = speed of light	time dilation
$L = L_0 \sqrt{1 - \frac{v^2}{c^2}}$	$L$ = contracted length $L_0$ = proper length $v$ = velocity of moving reference frame $c$ = speed of light	length contraction
$m = \frac{m_0}{\sqrt{1 - \frac{v^2}{c^2}}}$	$m$ = relativistic mass $m_0$ = rest mass $v$ = speed of mass relative to observer $c$ = speed of light	relativistic mass
$mc^2 = m_0c^2 + E_k$	$m$ = relativistic mass $m_0$ = rest mass $c$ = speed of light $E_k$ = kinetic energy	total energy
$E_{k(\max)} = hf - W$	$E_{k(\max)}$ = maximum kinetic energy of photoelectron $h$ = Planck's constant $f$ = frequency of electromagnetic radiation $W$ = work function of metal	photoelectric effect
$p = \frac{h}{\lambda}$	$p$ = momentum $h$ = Planck's constant $\lambda$ = wavelength	momentum of photon
$\lambda = \frac{h}{mv}$	$\lambda$ = wavelength (of matter wave) $h$ = Planck's constant $m$ = mass $v$ = velocity	de Broglie wavelength

## Equations in Unit 8, Nuclear Physics

Equation	Variables	Name, if any
$N = N_0 \left(\frac{1}{2}\right)^{\frac{\Delta t}{T_{\frac{1}{2}}}}$	$N$ = quantity of sample remaining $N_0$ = quantity of original sample $\Delta t$ = elapsed time $T_{\frac{1}{2}}$ = half-life	radioactive decay