

Chapter 11 (Projectiles + Circular Motion)

Projectiles

Horizontally - velocity is constant

$$v = \frac{\Delta d}{\Delta t}$$

Vertically - constant acceleration

$$a = \frac{\Delta v}{\Delta t} \quad v_{ave} = \frac{\Delta d}{\Delta t}$$

$$\Delta d = v_1 \Delta t + \frac{1}{2} a (\Delta t)^2$$

$$\Delta d = v_2 \Delta t - \frac{1}{2} a (\Delta t)^2$$

$$v_2^2 = v_1^2 + 2a\Delta d$$

For projectiles returning to the same level:

$$\Delta t = \frac{2v \sin \theta}{g} \quad \Delta d_h = \frac{v^2 \sin 2\theta}{g} \quad H = \frac{v^2 \sin^2 \theta}{2g}$$

Circular Motion

$$a_c = \frac{v^2}{r} = \frac{4\pi^2 r}{T^2} = 4\pi^2 r f^2$$

FBDs are important to see what expression
 you will use for F_{net} (centripetal force)

\Rightarrow \rightarrow

Chapter 12 (Planetary Mechanics)

Kepler's Laws:

1. elliptical orbits
2. sweep equal areas in equal times

Graphing
 r^3 vs T^2

slope = K

3. $K = \frac{r^3}{T^2}$ (unique for any central body)

Newton's Law of Universal Gravitation

$$\vec{F}_g = \frac{Gm_1m_2}{r^2}$$

Newton's Hypothesis (and applications)

$$F_g = F_c$$

m_2 is the orbiting mass

$$\frac{Gm_1m_2}{r^2} = m_2 a_c$$

where

$$a_c = \frac{v^2}{r} = \frac{4\pi^2 r}{T^2} = 4\pi^2 r f^2$$

Geostationary / Geosynchronous ($T = 24$ h for a satellite)

Chapter 13 (SHM)

- d-t, v-t, a-t, F-t graphs + how they relate to each other
- d-t, v-t, PE-t, KE-t, TE-t graphs + how they relate to each other.
- Period of a pendulum: $T = 2\pi\sqrt{\frac{l}{g}}$

Graphing T^2 vs l : $T^2 = \frac{4\pi^2}{g} l$
slope

- Period of a mass-spring system: $T = 2\pi\sqrt{\frac{m}{k}}$

Graphing T^2 vs m : $T^2 = \frac{4\pi^2}{k} m$
slope

- Conservation of Energy: $E_{total} = E'_{total}$

Pendulum

$$E_k = \frac{1}{2}mv^2$$

$$+ E_g = mgh$$

$$E_k = \frac{1}{2}mv^2$$

$$+ E_e = \frac{1}{2}kx^2$$

mass-spring system

$$F_a = kx$$