

From HW (pp 580)

4. $r = 5.30 \times 10^{-11} \text{ m}$

$m_1 = 9.109 \times 10^{-31} \text{ kg}$ (electron)

$m_2 = 1.673 \times 10^{-27} \text{ kg}$ (proton)

$$F_g = \frac{Gm_1m_2}{r^2}$$

5. VENUS:

m_1 $m = 68 \text{ kg}$

$F_g = 575 \text{ N}$

$r = 6.31 \times 10^6 \text{ m}$

m_2 $M_{\text{venus}} = ?$

$$F_g = \frac{Gm_1m_2}{r^2}$$

$$m_2 = \frac{F_g r^2}{Gm_1}$$

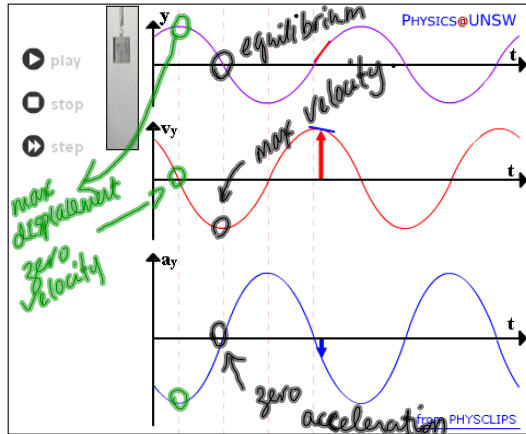
$$m_2 = \frac{(575 \text{ N})(6.31 \times 10^6 \text{ m})^2}{(6.67 \times 10^{-11} \text{ N} \cdot \text{m}^2 / \text{kg}^2)(68 \text{ kg})}$$

OR $F_g = \frac{Gm_1m_2}{r^2}$ ← object

$F_g = mg$

$m_2 = 5.0 \times 10^{24} \text{ kg}$

SIMPLE HARMONIC MOTION



← slope of tangent gives the velocity
 ← slope of tangent gives the acceleration

max displacement
 zero velocity

(no stretch/compression ∴ no force ∴ no acc.)

Pendulum:

displacing from the lowest point (equilibrium) and giving the pendulum gravitational potential energy which is transformed into kinetic energy.

RECALL: $E_{total} = E'_{total}$
 $E_g + E_k = E'_g + E'_k$ LAW OF CONSERVATION OF MECHANICAL ENERGY

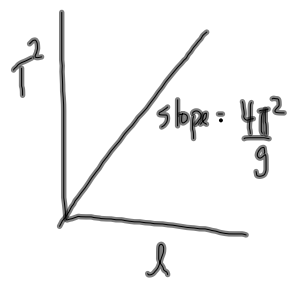
$E_g = mgh$
 $E_k = \frac{1}{2}mv^2$

$T = 2\pi\sqrt{\frac{l}{g}}$

square both sides → for small amplitudes, the period of a pendulum depends only on its length.

$T^2 = \frac{4\pi^2}{g}l$

$y = mx + b$



Harmonic Oscillator (Mass/Spring System)



When the mass is displaced from its equilibrium position, the mass will have elastic potential energy which is transformed into kinetic energy:

$$E_{\text{total}} = E'_{\text{total}}$$

$$E_e + E_k = E'_e + E'_k$$

LAW OF
CONSERVATION
OF
MECHANICAL
ENERGY.

$$E_e = \frac{1}{2} kx^2$$

$$F_a = kx \text{ (restoring force is: } F = -kx \text{)}$$

Period of
oscillation:

$$T = 2\pi \sqrt{\frac{m}{k}}$$

k is the
Spring
constant

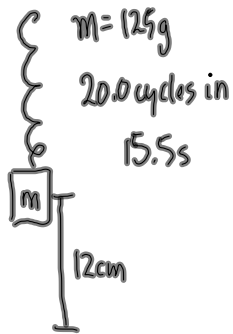
A graph of
 T^2 vs m will

$$T^2 = \frac{4\pi^2 m}{k}$$

$$(y = mx + b)$$

linear with a slope of $\frac{4\pi^2}{k}$

MP/606



a) Period $T = \frac{15.5 \text{ s}}{20.0 \text{ cycles}}$ $T = \frac{\Delta t}{N}$

$$T = 0.775 \text{ s}$$

b) $k = ?$ $T = 2\pi \sqrt{\frac{m}{k}}$

$$T^2 = 4\pi^2 \frac{m}{k}$$

$$k = \frac{4\pi^2 m}{T^2}$$

c) total energy:

$$E_e = \frac{1}{2} k x^2$$

$$E_e = \frac{1}{2} (8.22 \text{ N/m}) (0.120 \text{ m})^2$$

$$E_e = 0.0592 \text{ J}$$

$$k = \frac{4\pi^2 (0.125 \text{ kg})}{(0.775 \text{ s})^2}$$

$$k = 8.22 \text{ N/m}$$

d) the maximum velocity (at equilibrium, $E_e = 0$)

max stretch @ equilib

$$E_{\text{total}} = E'_{\text{total}}$$

$$E_e + E_k = E'_e + E'_k$$

$$E_e = E'_k$$

$$0.0592 \text{ J} = \frac{1}{2} (0.125 \text{ kg}) v^2$$

$$v = 2.75 \text{ m/s}$$

e) v at 10 cm ?

max stretch @ 10 cm

$$E_{\text{total}} = E'_{\text{total}}$$

$$E_e + E_k = E'_e + E'_k$$

$$0.0592 \text{ J} = \frac{1}{2} (8.22 \text{ N/m}) (0.100 \text{ m})^2 + \frac{1}{2} (0.125 \text{ kg}) v^2$$

$$0.0592 \text{ J} = 0.0411 \text{ J} + \frac{1}{2} (0.125 \text{ kg}) v^2$$

$$0.0181 \text{ J} = \frac{1}{2} (0.125 \text{ kg}) v^2$$

$$v = \pm 0.538 \text{ m/s}$$